

Automation for a Changing World

AX-864E Package Installation User Manual

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Chapter 1: Package Installation

1.1 Overview

This document describes how to install the AX-8xxEP0 Series_1.0.0.0 package in the CODESYS V3.5 SP14 software. After the installation, the device related configuration will build-in CODESYS software and user can use the IEC program, configuration, and functions to implement the project.

1.2 Software and Package Download

Please download the Codesys software as below link.

- Codesys standard software
<http://www.deltaww.com/services/DownloadCenter2.aspx?secID=8&pid=2&tid=0&CID=06&itemID=060210&typeID=1&downloadID=&title=&dataType=8;3;&check=1&hl=en-US>
- Package: AX-8xxEP0 Series_1.0.0.0



1.3 Package Installation

Please install the Codesys software first and follow the below step to install package.

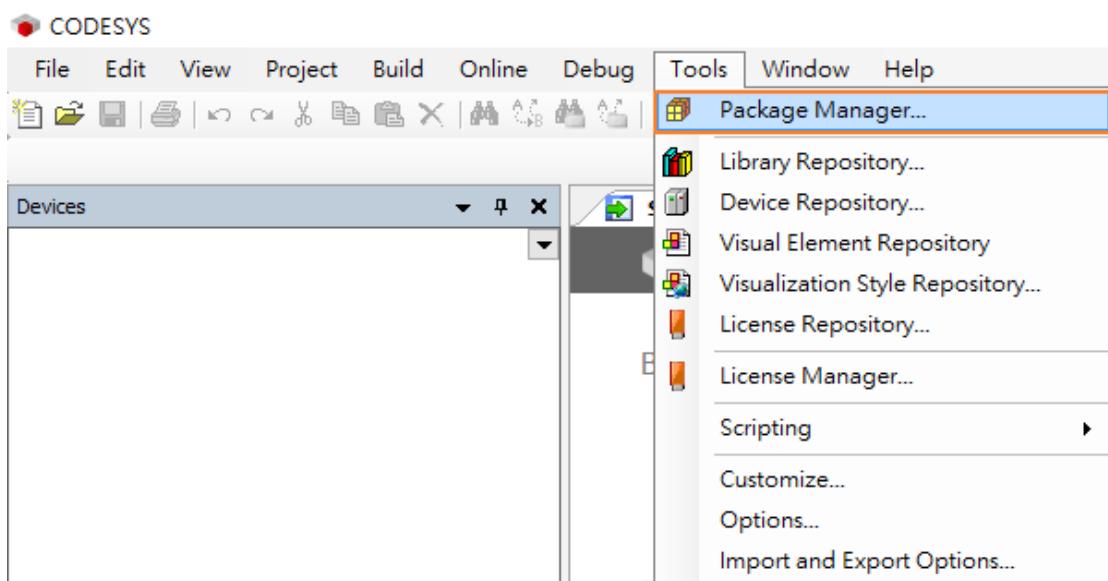
1. Download the Package in Delta download center



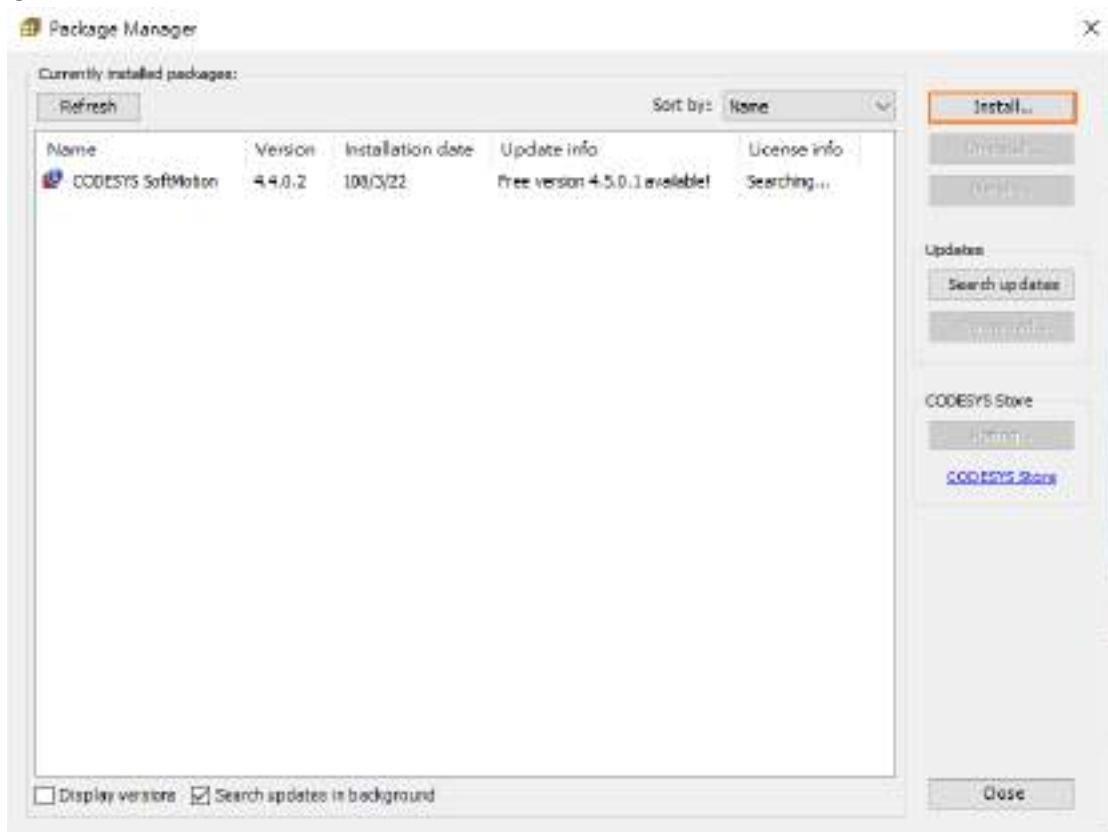
2. Open the Codesys Development Software



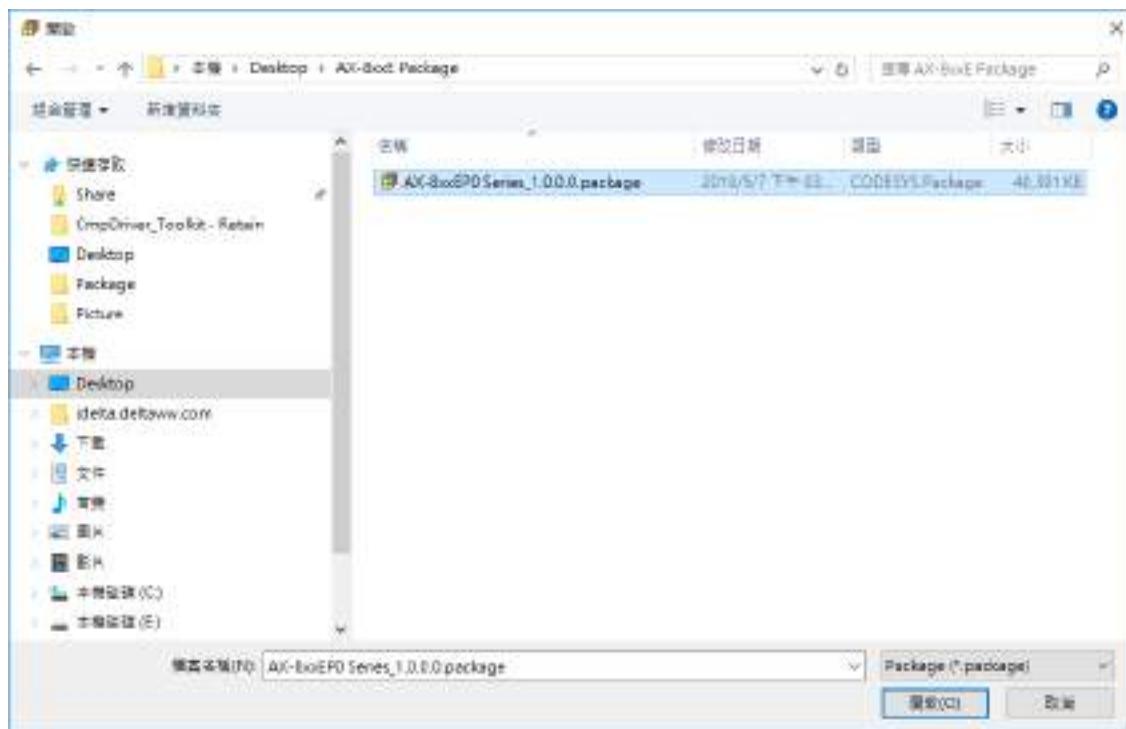
-
3. Click “Tools” → “Package Manager”



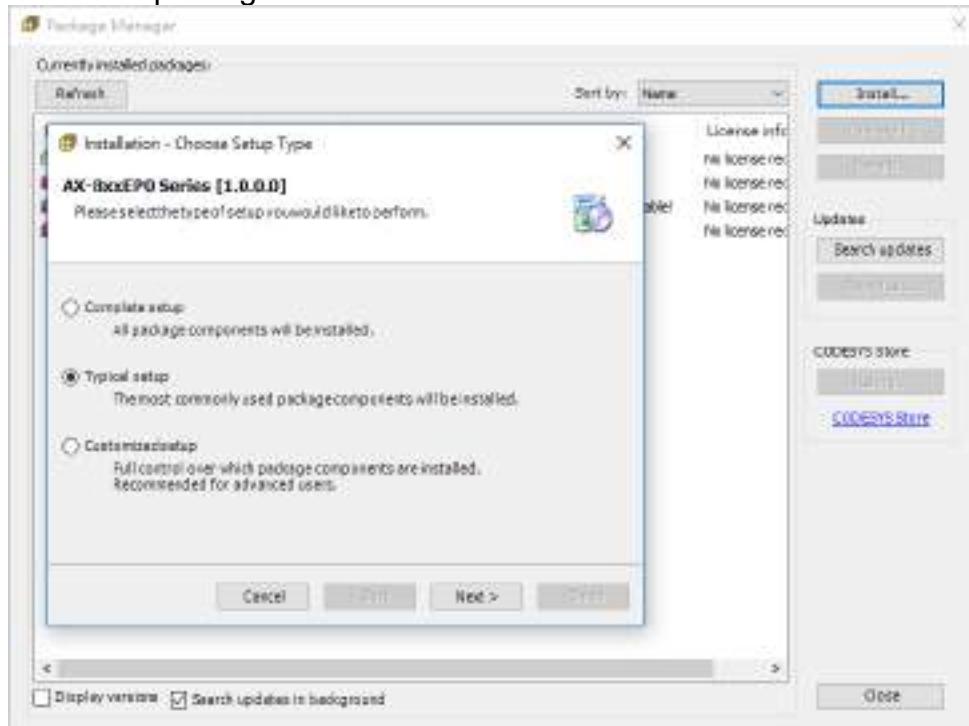
4. Click “Install”



5. Select the Package - AX-BxxEP0 Series_1.0.0.0



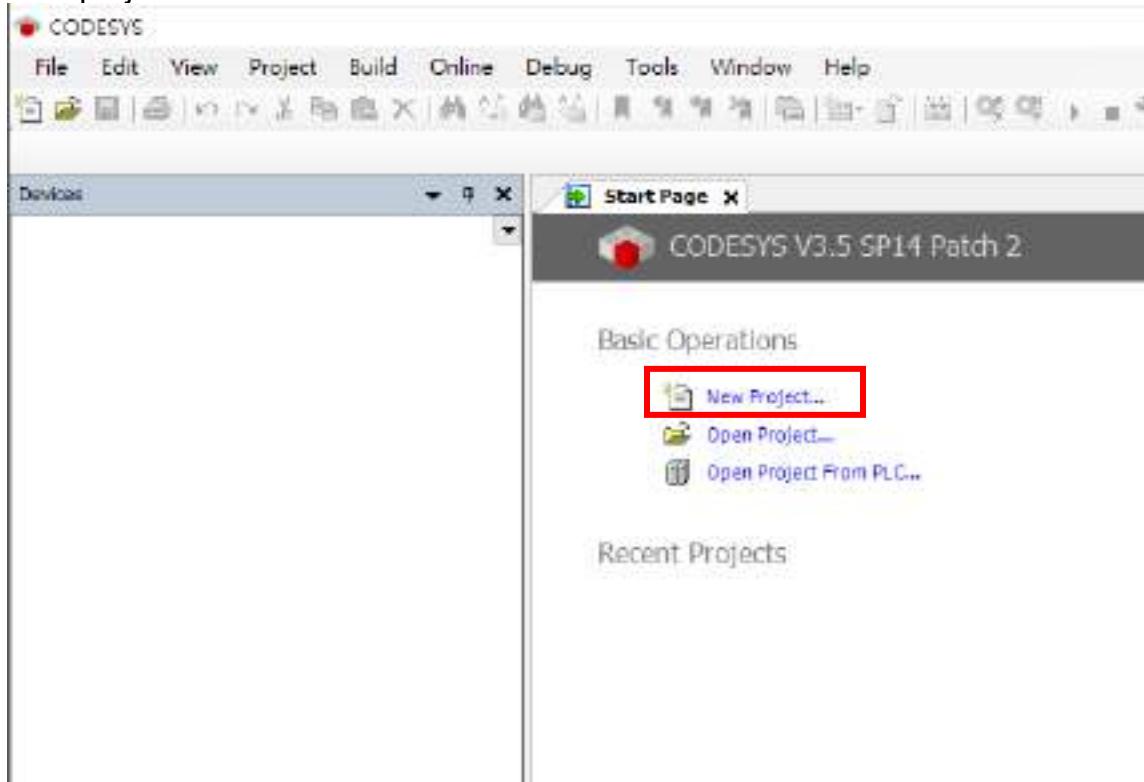
6. Install the package



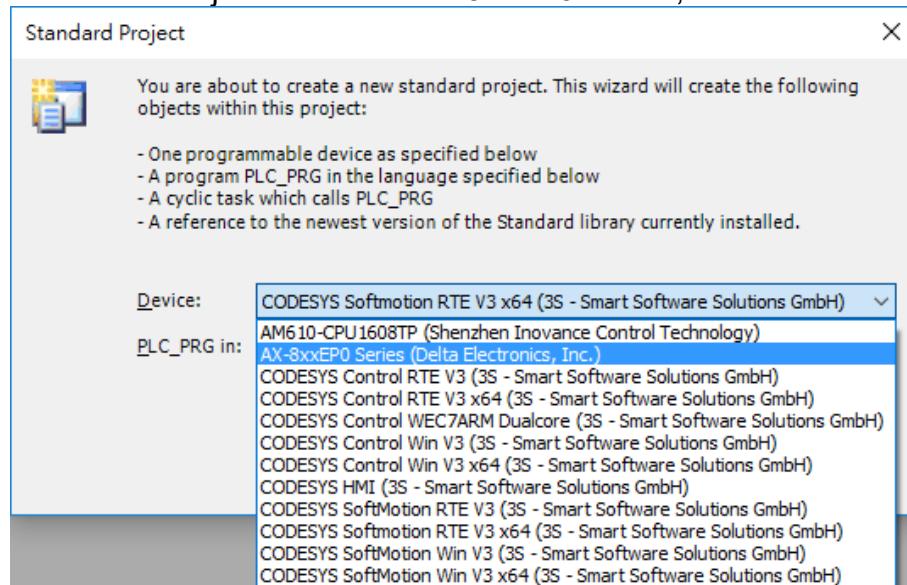
1.4 Open AX-8 Series Configuration

After the package installation, user can follow the below steps to create the AX8 series project and config the related program, function, and configuration.

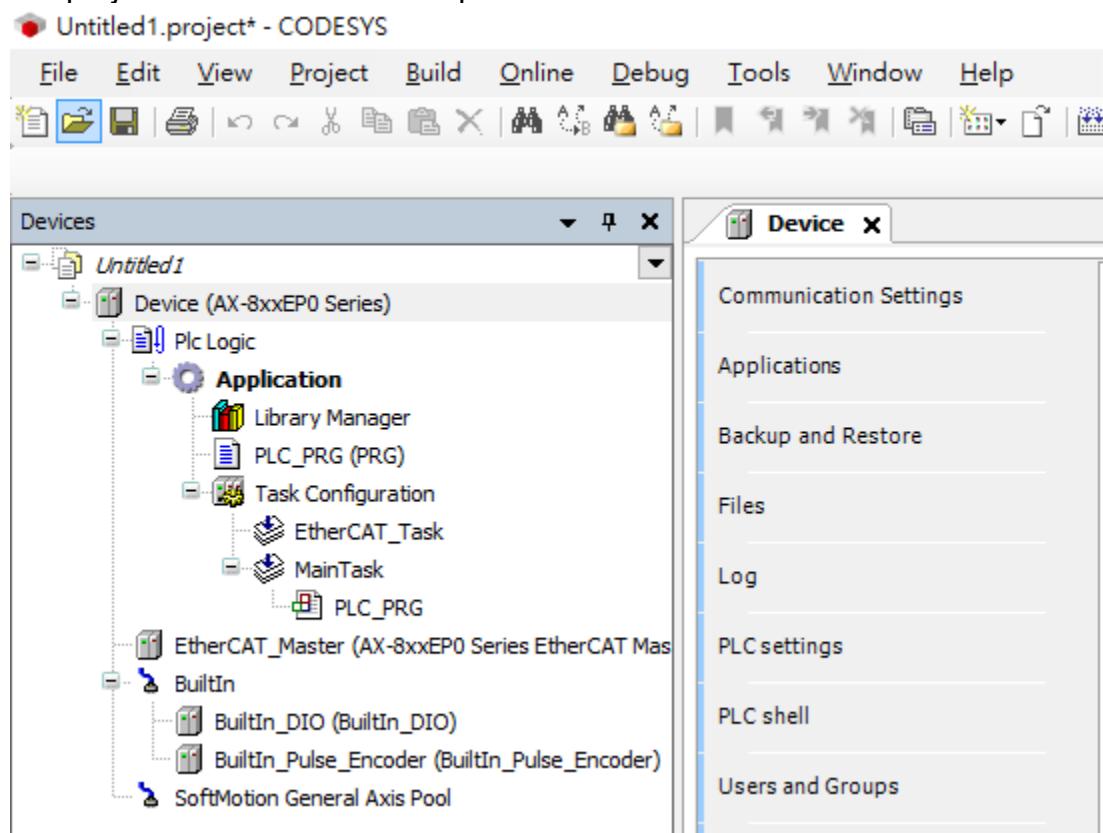
1. New project



2. Choose Standard Project > Device: AX-8xxEP0 Series, and choose the PLC_PRG.



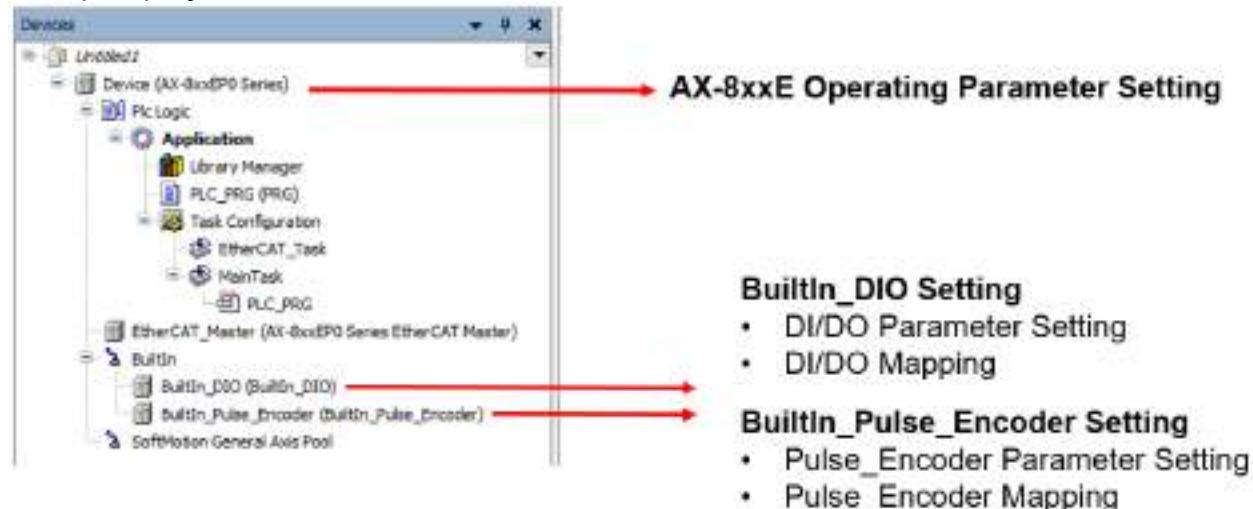
3. The project will create ad below picture.



1.5 AX-8 Series Parameter

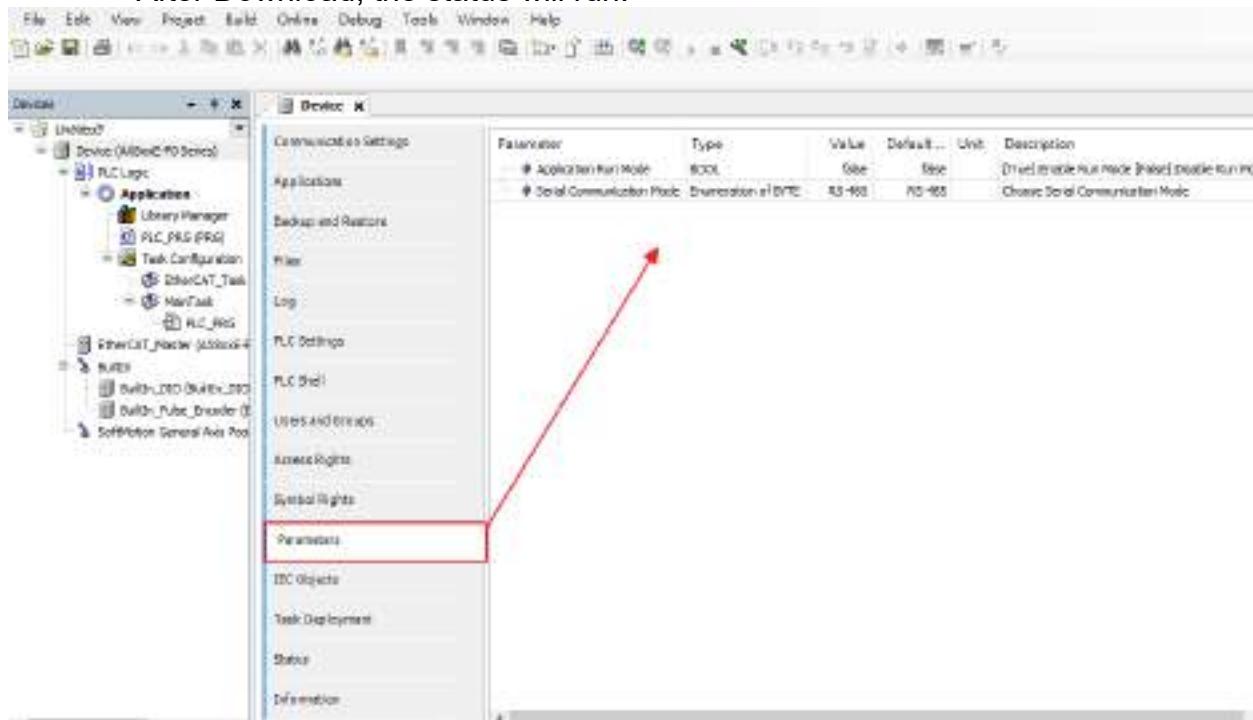
AX-8 Controller parameter setting in Codesys software.

1. Open project



4. Application Run Mode : Set RTE and PLC "Run" status when controller active

- Setting Value : True, False
- Default Value : False
- Offline can change the setting
- After Download, the status will run.



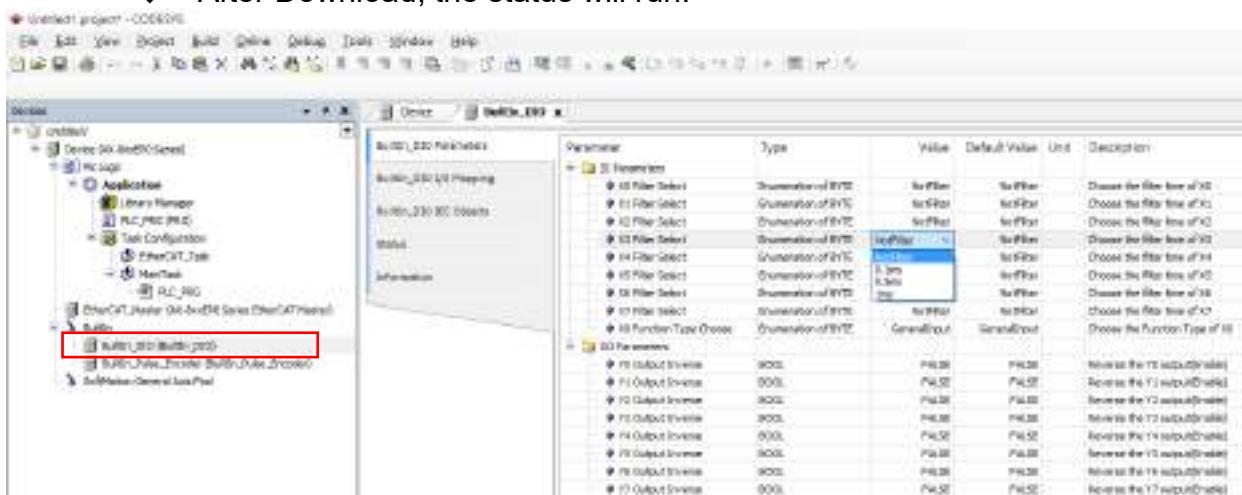
5. Serial Communication Mode :

- Setting Value : RS-485, RS-422, SSI
- Default Value : RS-485
- Offline can change the setting
- After Download, the status will run.
- Windows device administrator default comport : COM3

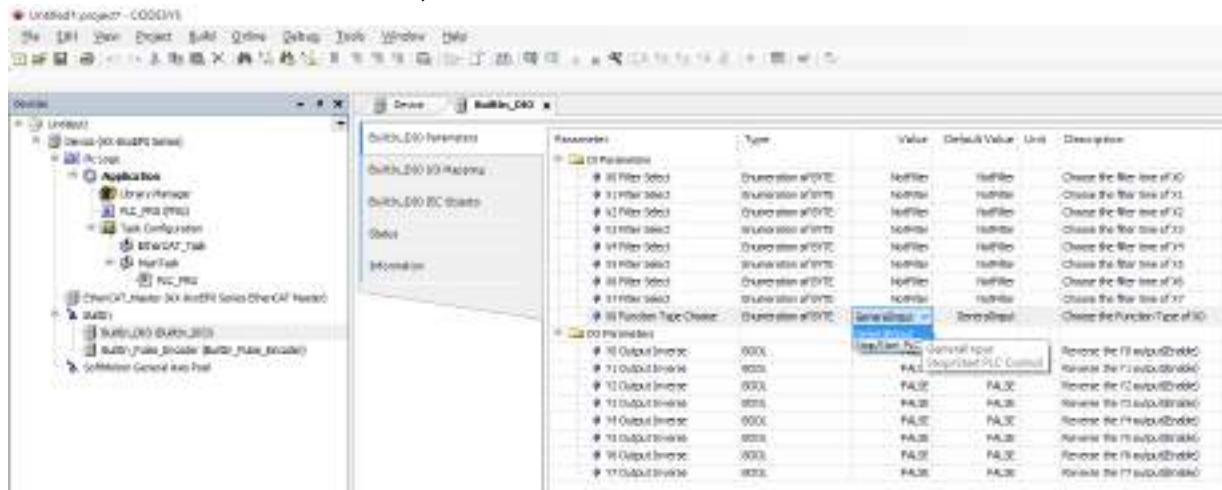


6. BuiltIn_DIO Parameter:

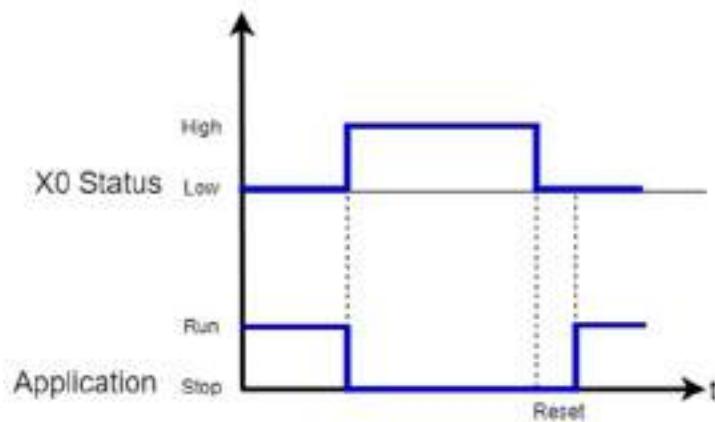
- DI Filter Select : Set X0~X7 input filter time
 - ◆ Setting Value : Not Filter、0.1ms、0.5ms、1ms
 - ◆ Default Value : Not Filter
 - ◆ Offline can change the setting
 - ◆ After Download, the status will run.
- DO Output Inverse : Set Y0~Y7 out reserve
 - ◆ Setting Value : True、False
 - ◆ Default Value : False
 - ◆ Offline can change the setting
 - ◆ After Download, the status will run.



- X0 Function Type Choose : Set X0 as general output or special software functions
 - ◆ Setting Value :
 - A. General Input
 - B. Stop/Start PLC Control
 - ◆ Default Value : General Input
 - ◆ Offline can change the setting
 - ◆ After Download, the status will run.

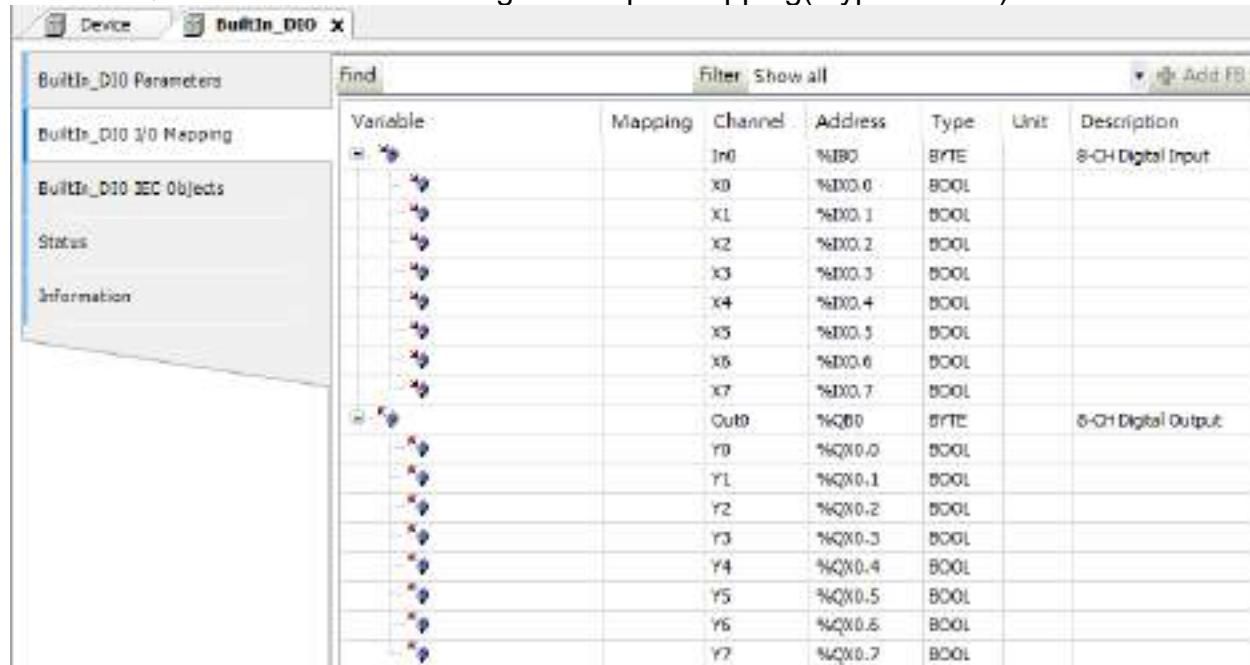


- ❖ Note: Stop/Start PLC Control Timing diagram
 - ◆ When X0 is Low, Application → Reset → Run
 - ◆ When X0 is High, Application Stop



7. BuiltIn_DIO I/O Mapping :

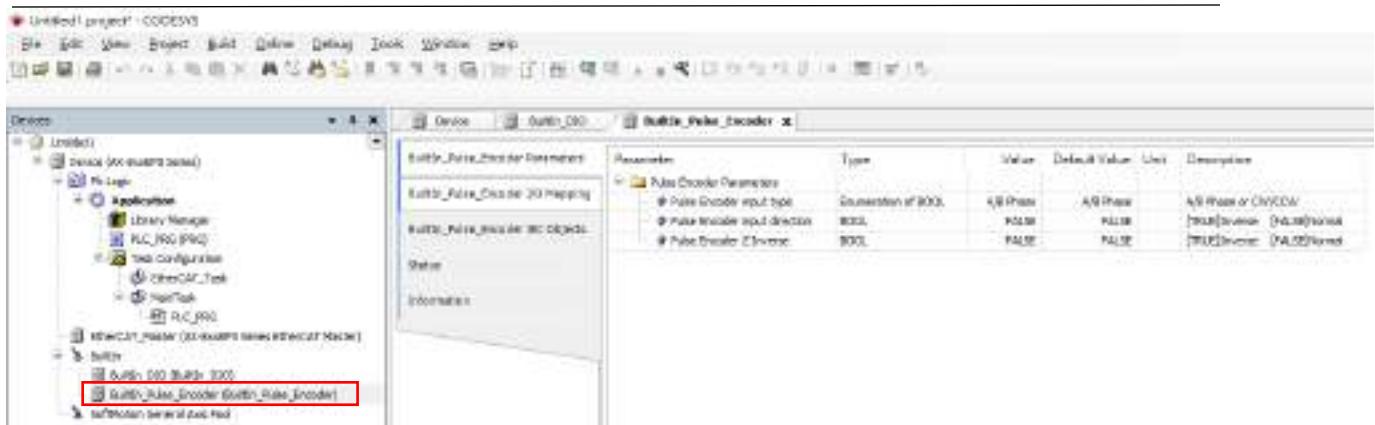
- I/O Mapping : Input or output Mapping
 - ◆ Input 0 or Output 0 Mapping (Type: Byte)
 - ◆ X0~X7 or Y0~Y7 Single in/output Mapping(Type: BOOL)



Variable	Mapping	Channel	Address	Type	Unit	Description
	In0		%IB0	BYTE		8-CH Digital Input
	X0		%DIO.0	BOOL		
	X1		%DIO.1	BOOL		
	X2		%DIO.2	BOOL		
	X3		%DIO.3	BOOL		
	X4		%DIO.4	BOOL		
	X5		%DIO.5	BOOL		
	X6		%DIO.6	BOOL		
	X7		%DIO.7	BOOL		
	Out0		%QB0	BYTE		8-CH Digital Output
	Y0		%QDI.0	BOOL		
	Y1		%QDI.1	BOOL		
	Y2		%QDI.2	BOOL		
	Y3		%QDI.3	BOOL		
	Y4		%QDI.4	BOOL		
	Y5		%QDI.5	BOOL		
	Y6		%QDI.6	BOOL		
	Y7		%QDI.7	BOOL		

8. BuiltIn_Pulse_Encoder Parameter:

- Pulse Encoder input type :
 - ◆ Setting Value : A/B Phase 、 CW/CCW
 - ◆ Default Value : A/B Phase
 - ◆ Offline can change the setting
 - ◆ After Download, the status will run.
- Pulse Encoder input direction :
 - ◆ Setting Value : True(Inverse) 、 False(Normal)
 - ◆ Default Value : False
 - ◆ Offline can change the setting
 - ◆ After Download, the status will run.
- Pulse Encoder Z Inverse :
 - ◆ Setting Value : True(Inverse) 、 False(Normal)
 - ◆ Default Value : False
 - ◆ Offline can change the setting
 - ◆ After Download, the status will run.

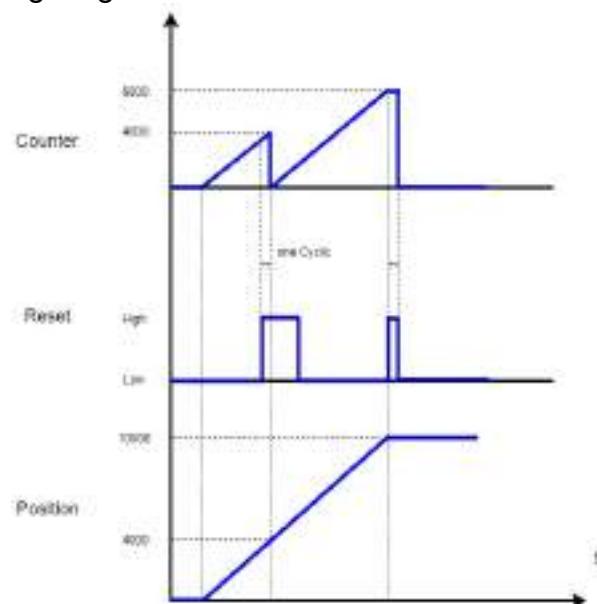


9. BuiltIn_Pulse_Encoder I/O Mapping:

- Pulse_Encoder Mapping : Pulse Encoder Input and Reset Mapping
 - ◆ Counter (Type : DINT)
 - ◆ Reset (Type: BOOL & Execution)

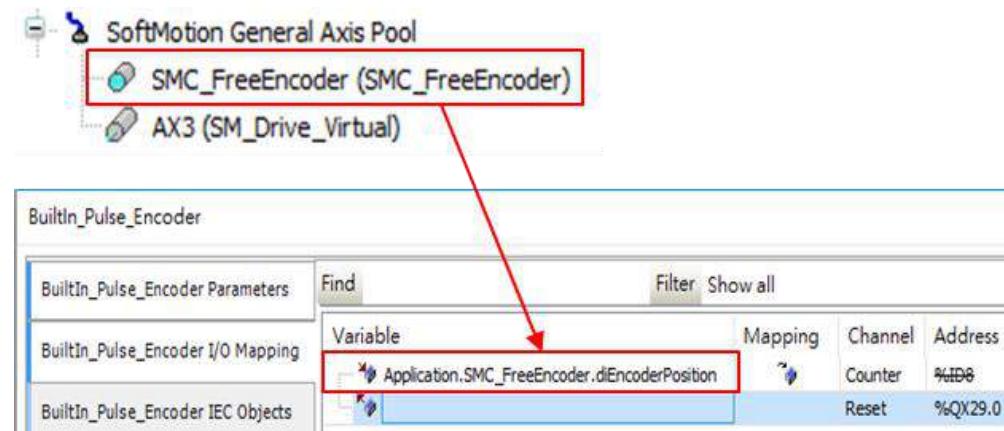
BuiltIn_Pulse_Encoder Parameters		Find: Filter: Show all						
BuiltIn_Pulse_Encoder I/O Mapping		Variable	Mapping	Channel	Address	Type	Unit	Description
		%C	Counter	%D1	DINT			Counter value
		%Q	Reset	%QX1.0	BOOL			Reset Counter value(Execution)

◆ ResetTiming diagram

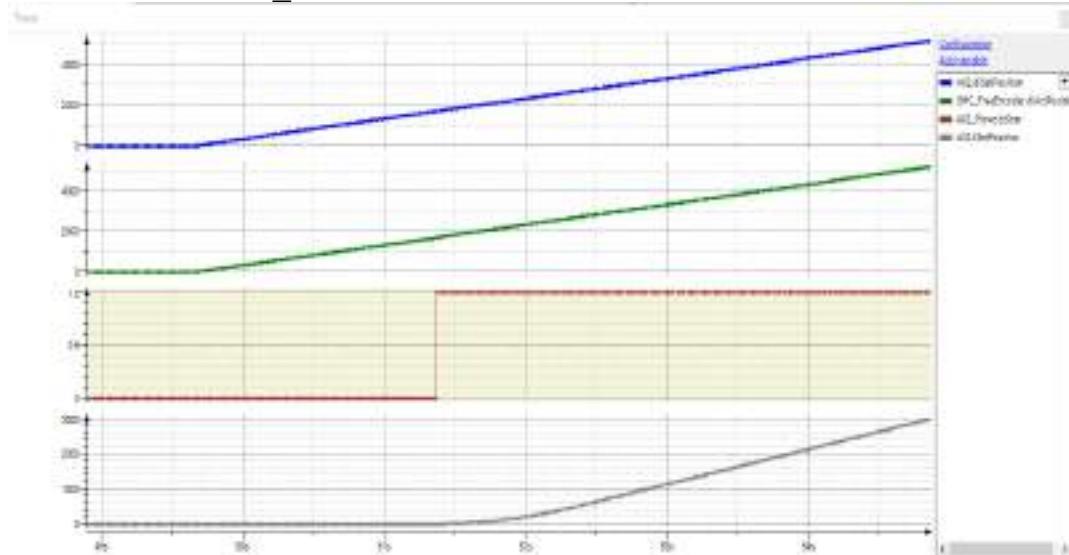


- Pulse_Encoder example :

- Add Device → Add “SMC_FreeEncode” and map with Counter 做



- Use Encoder of R1-EC5621 as output to AX-8xxE Pulse Encoder
- Use SMC_FreeEncoder as master axis and do GrarIn with virtual axis.



Chapter 2: CODESYS variables share to DIAScreen

2.1 Overview

DIAScreen have support to import variables of Codesys software. User can define the variables in Codesys development software and export the xml file of symbol configuration. Import the xml to DIAScreen to communicate between controller and Delta HMI functions.

Please download DAIScreen Installation in Website

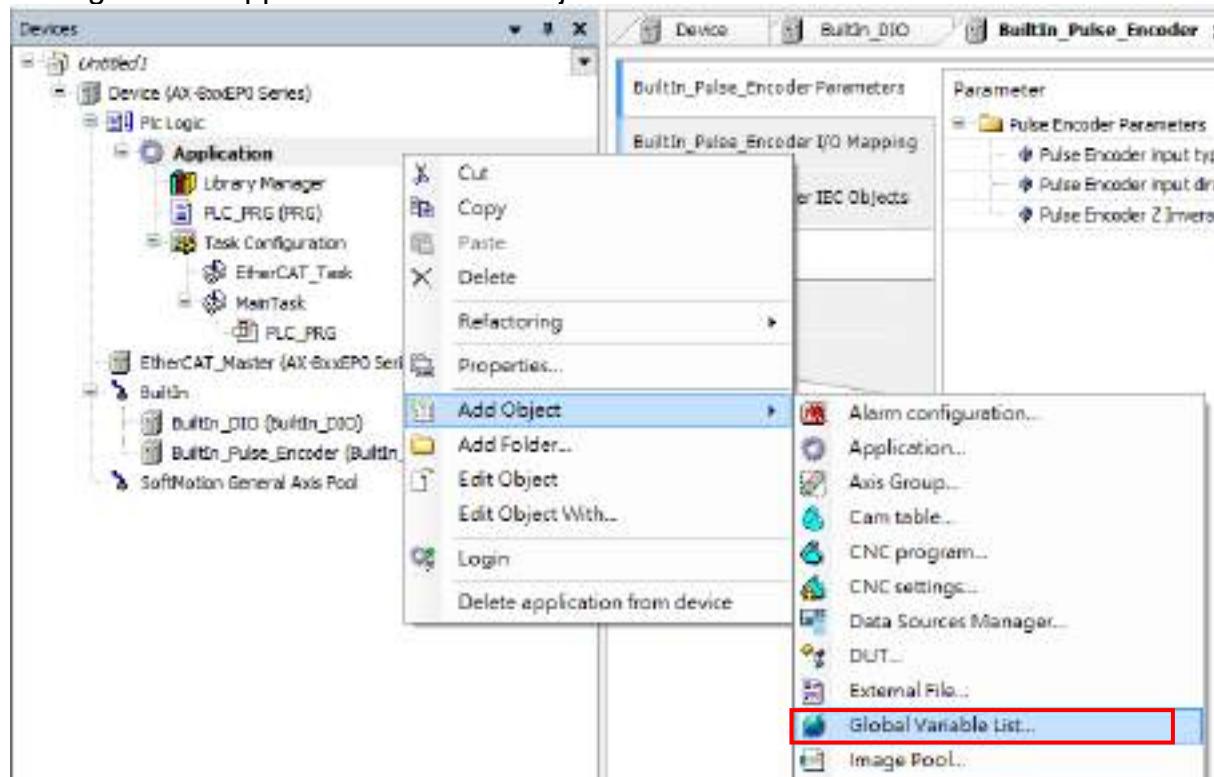
<http://www.deltaww.com/services/DownloadCenter2.aspx?secID=8&pid=2&tid=0&CID=06&itemID=060210&TypeID=1&downloadID=&title=&dataType=&check=0&hl=zh-TW>

Support PAC AX-8 series and DOP-100 series.

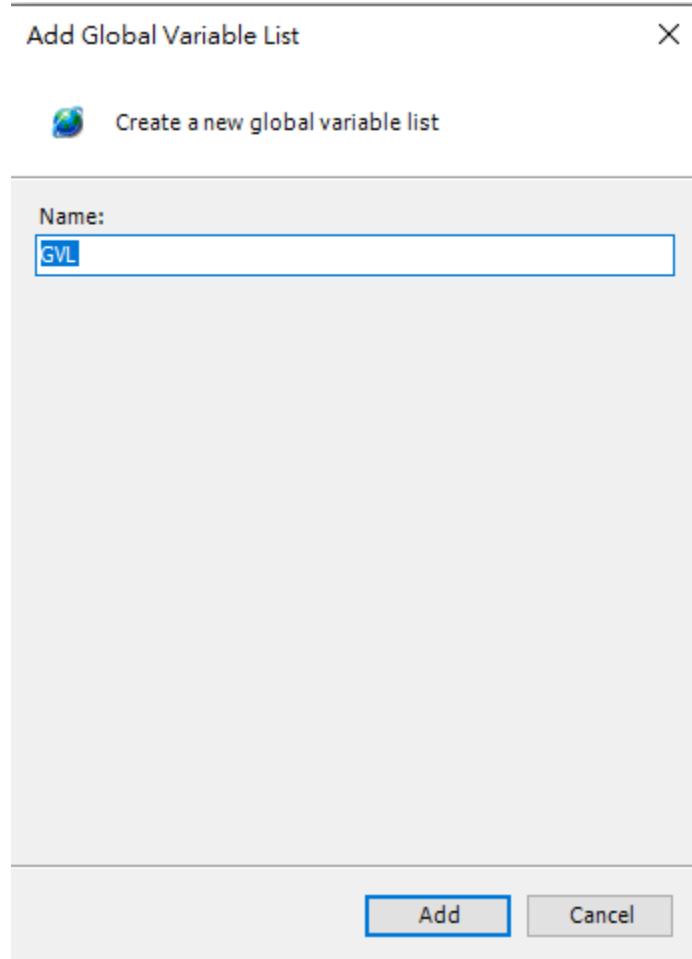
2.2 Export Variable in Codesys

Build the Global Variable list and export the symbol configuration.

1. Right click “Application” → “Add Object” → “Global Variable List”



2. Import the Global Variable list naming.

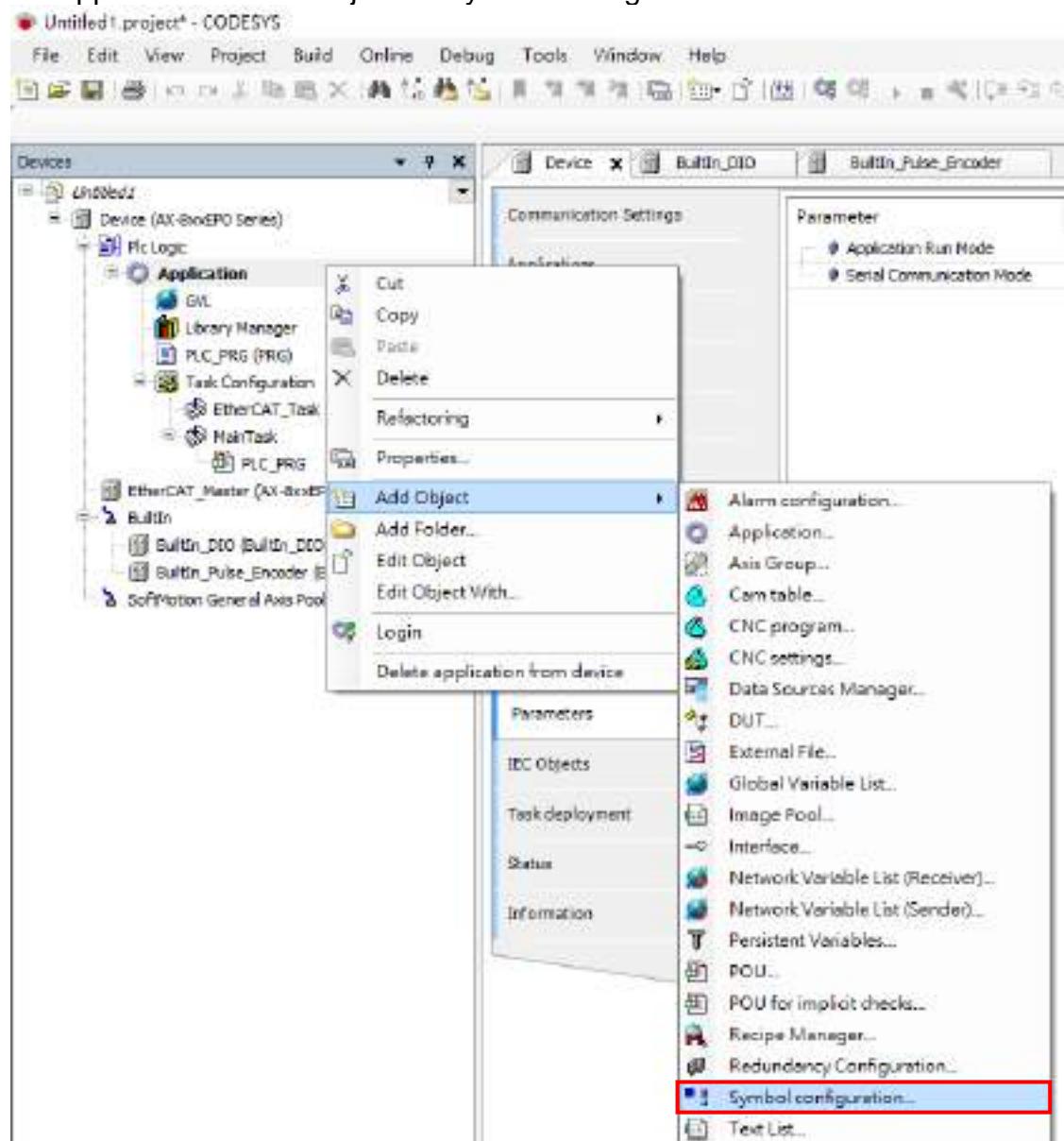


3. Build Variable in GVL

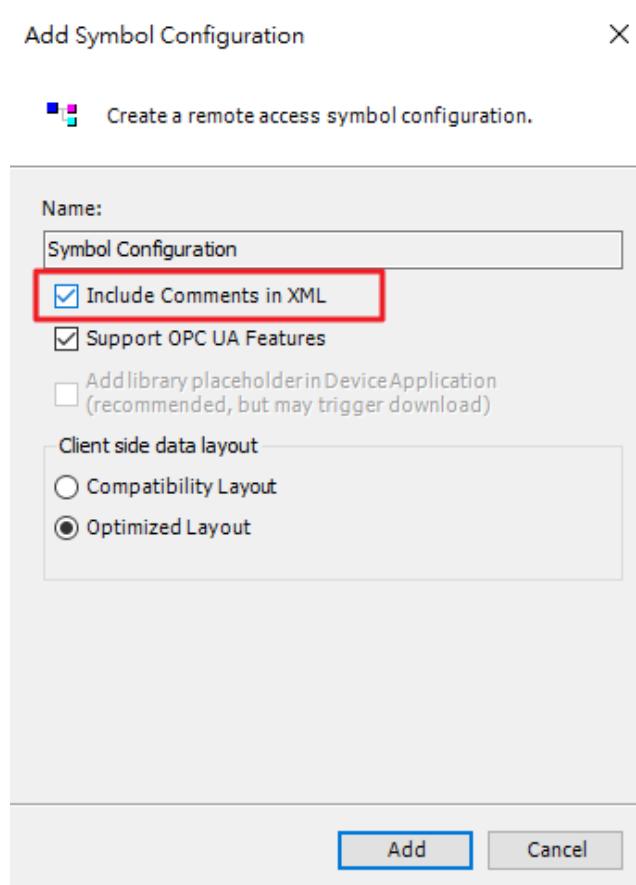
The screenshot shows the 'Library Manager' window with the title bar 'GVL'. On the left is a tree view of the project structure under 'Devices'. The 'Application' node is expanded, showing 'GVL' selected. The main area displays a table of variables:

Scope	Name	Address	Data type	Initializ
VAR_GLOBAL	Axis_1_MC_Halt_Aborted		BOOL	
VAR_GLOBAL	Axis_1_MC_Halt_Busy		BOOL	
VAR_GLOBAL	Axis_1_MC_Halt_Deceleration		UREAL	
VAR_GLOBAL	Axis_1_MC_Halt_Done		BOOL	
VAR_GLOBAL	Axis_1_MC_Halt_Error		BOOL	
VAR_GLOBAL	Axis_1_MC_Halt_ErrorID		SMC_ERROR	
VAR_GLOBAL	Axis_1_MC_Halt_Execute		BOOL	
VAR_GLOBAL	Axis_1_MC_Halt_Jerk		UREAL	
VAR_GLOBAL	Axis_1_MC_Power_Busy		BOOL	
VAR_GLOBAL	Axis_1_MC_Power_DriveStart		BOOL	
VAR_GLOBAL	Axis_1_MC_Power_DriveStartRealState		BOOL	
VAR_GLOBAL	Axis_1_MC_Power_Enable		BOOL	
VAR_GLOBAL	Axis_1_MC_Power_Error		BOOL	
VAR_GLOBAL	Axis_1_MC_Power_ErrorID		SMC_ERROR	
VAR_GLOBAL	Axis_1_MC_Power_RegulatorOn		BOOL	
VAR_GLOBAL	Axis_1_MC_Power_RegulatorRealState		BOOL	
VAR_GLOBAL	Axis_1_MC_Power_Status		BOOL	

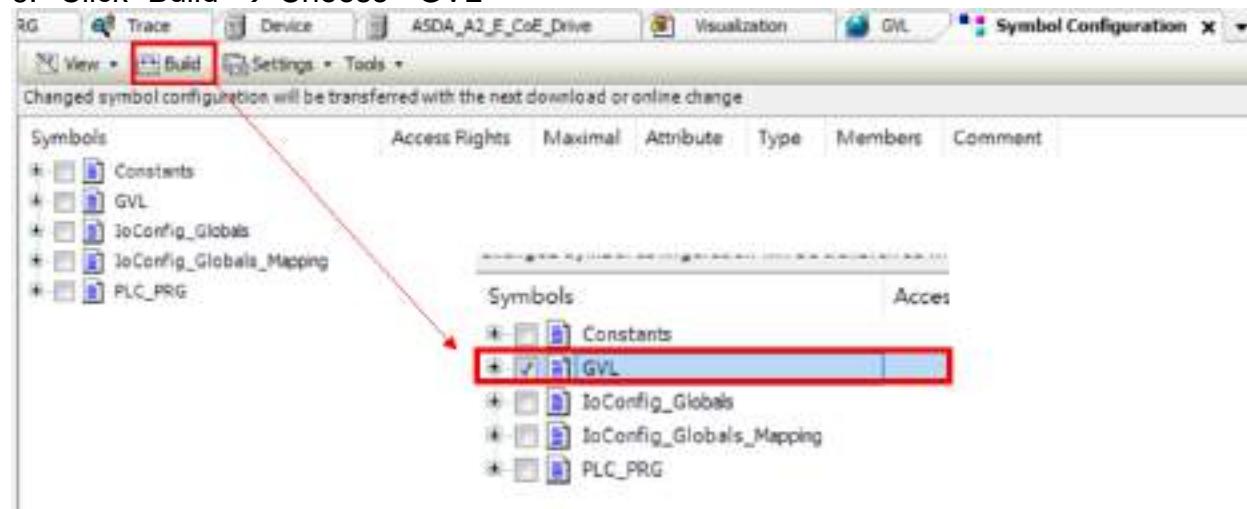
4. Application → Add Object → Symbol Configuration



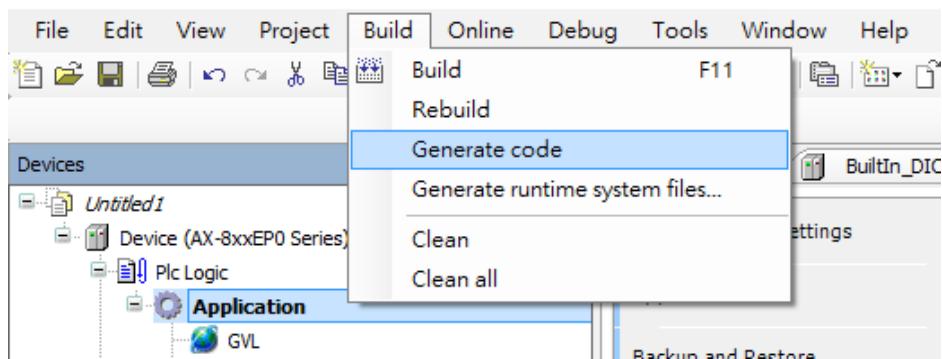
5. Choose “Include Comments in XML”



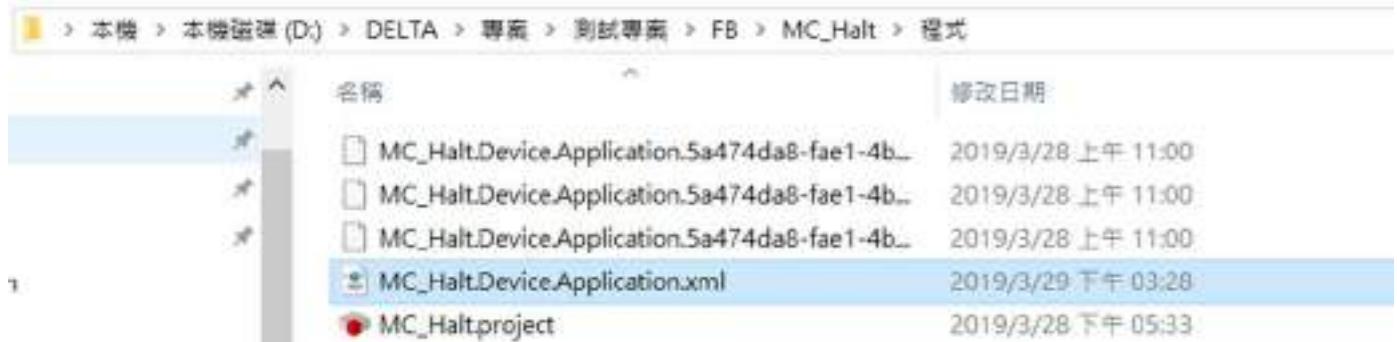
6. Click “Build” → Choose “GVL”



7. Go to toolbar → “Build” → “Generate code”



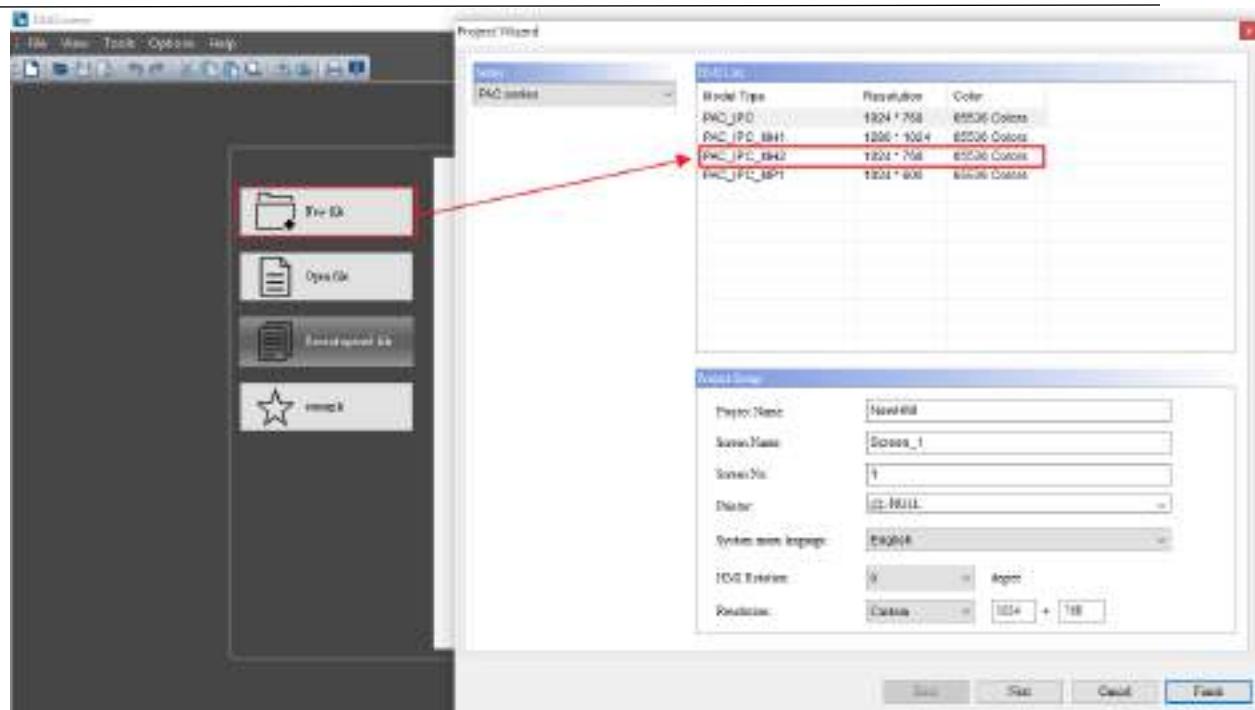
8. The xml will in the assign folder.



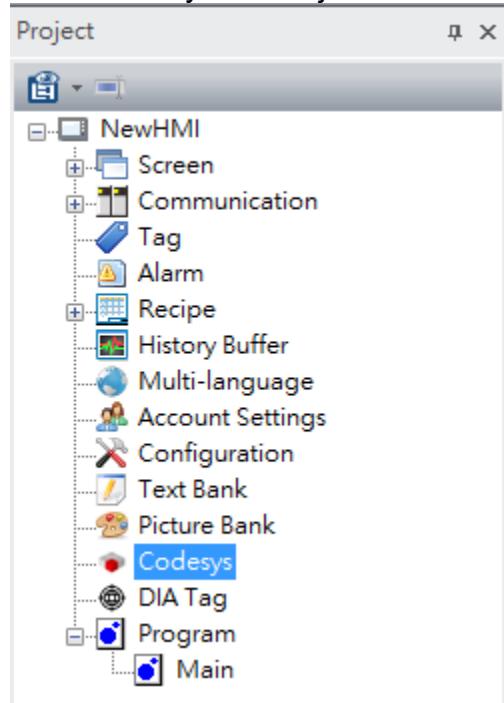
2.3 DIAScreen with PAC AX-8 Series

1. Open DAIScreenV1.0 → “New File” → Choose “AX8xxE” model.

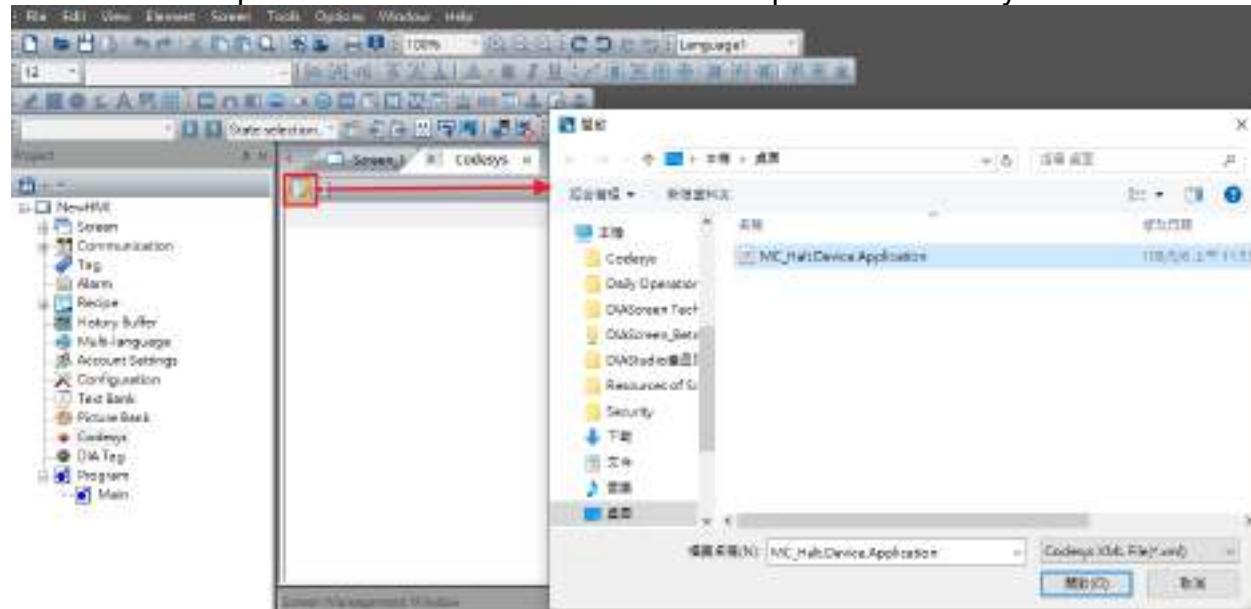




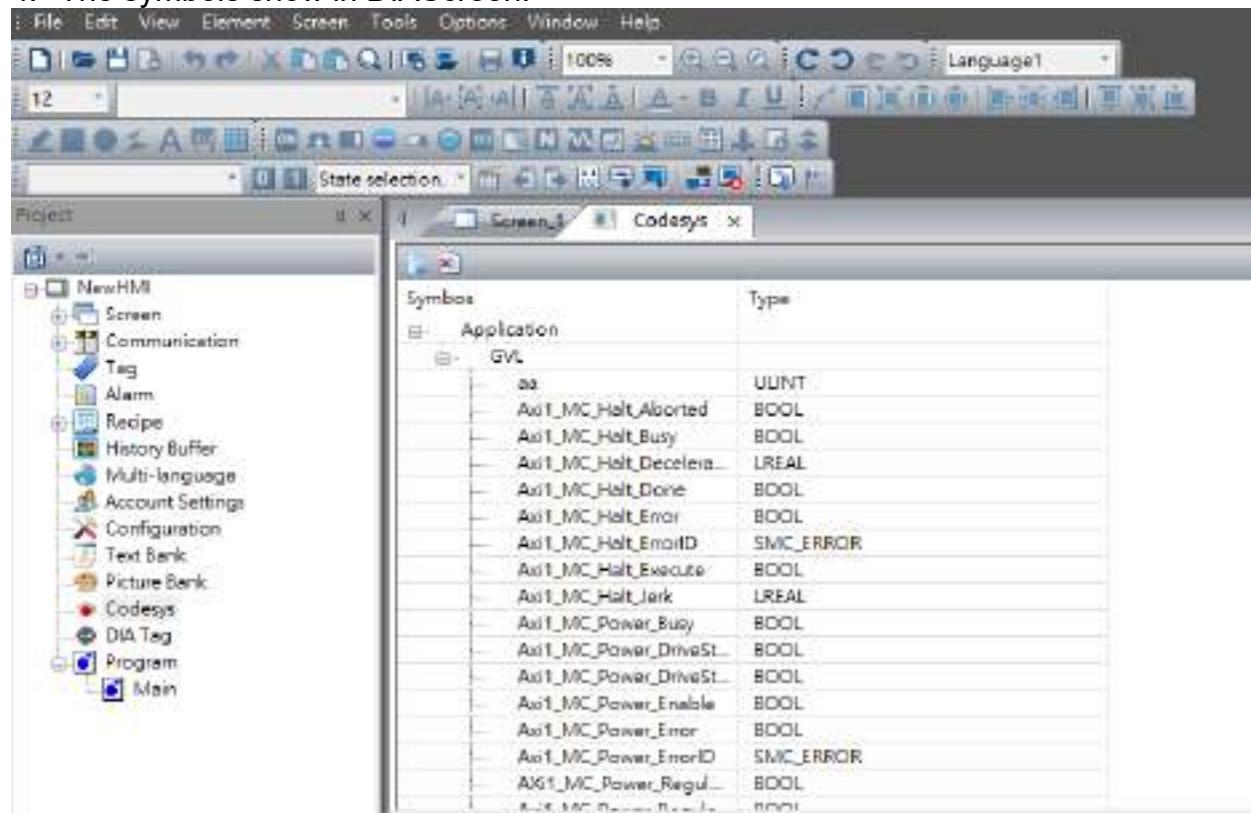
2. Go to “Codesys” in Project Tree



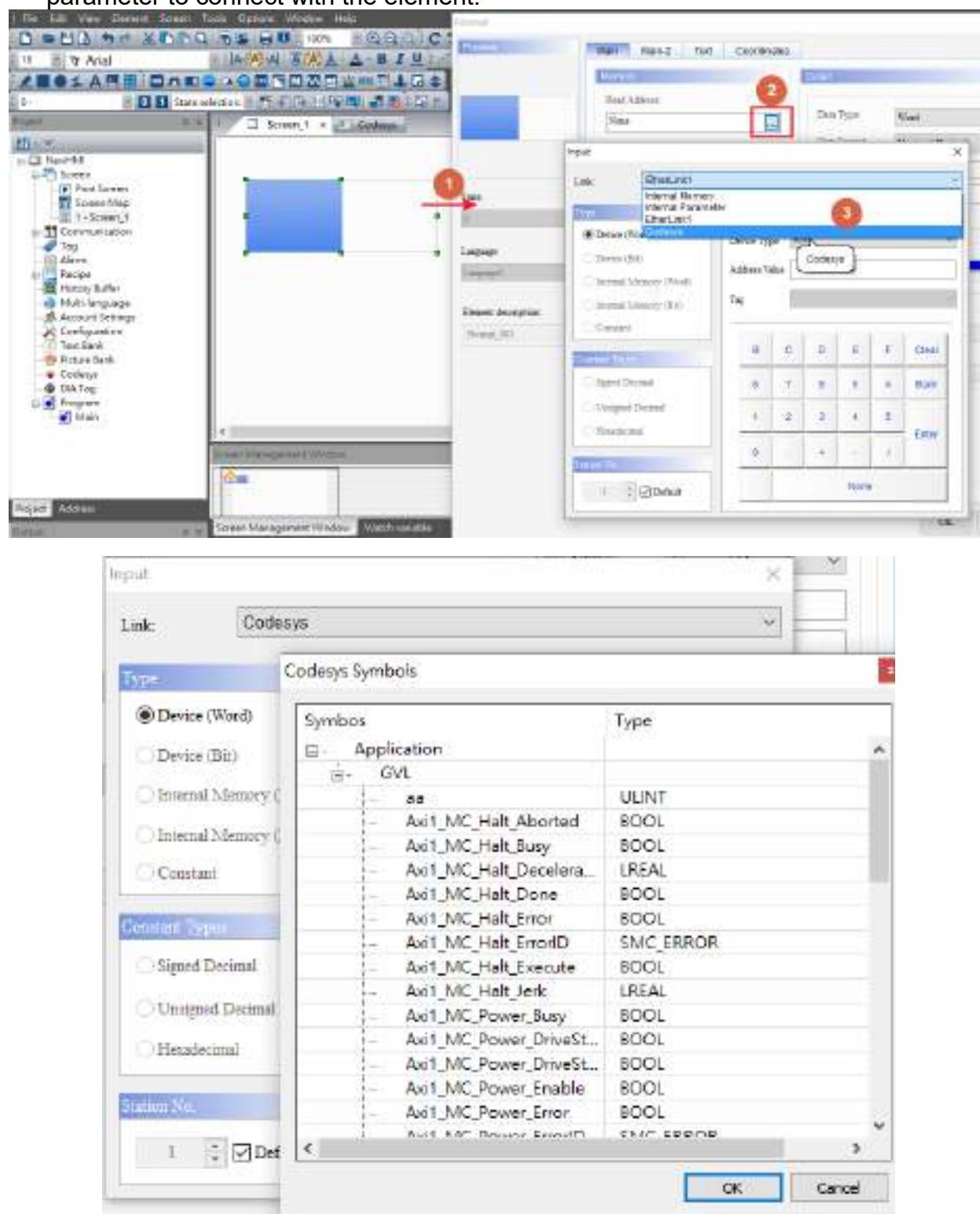
3. Click the “Import” and choose the xml file which export from Codesys.



4. The symbols show in DIAScreen.

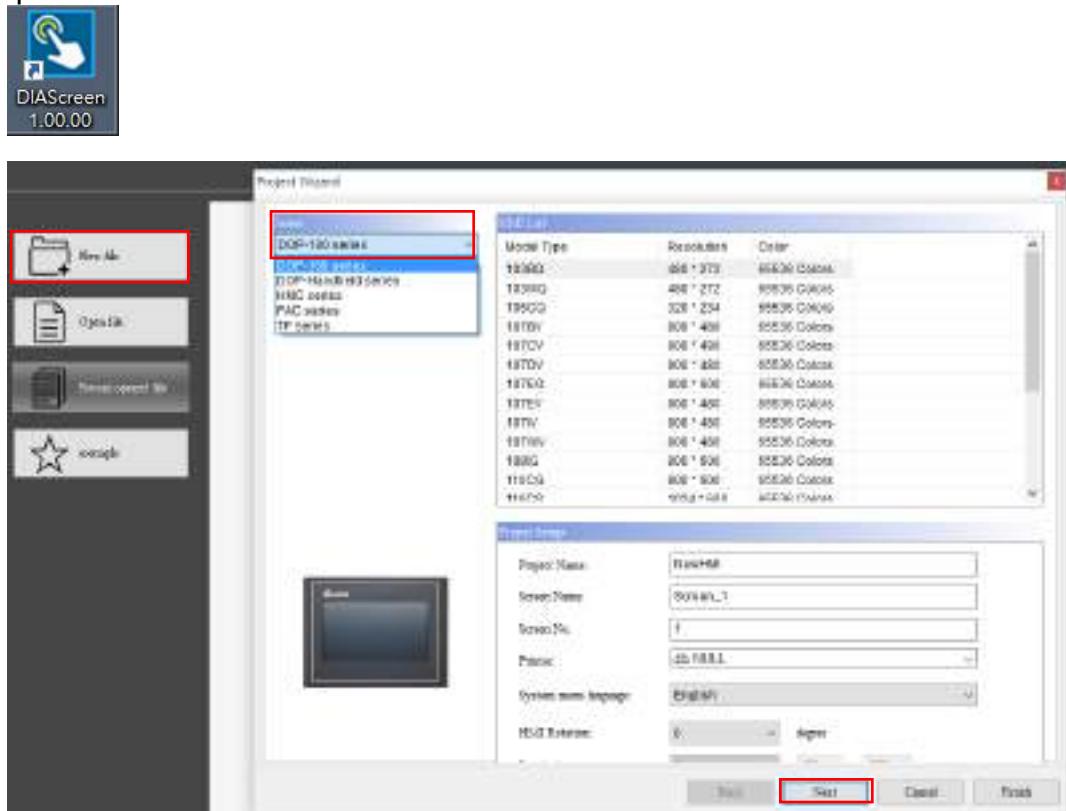


5. Insert the Element and Double click the element. User can choose the Codesys parameter to connect with the element.

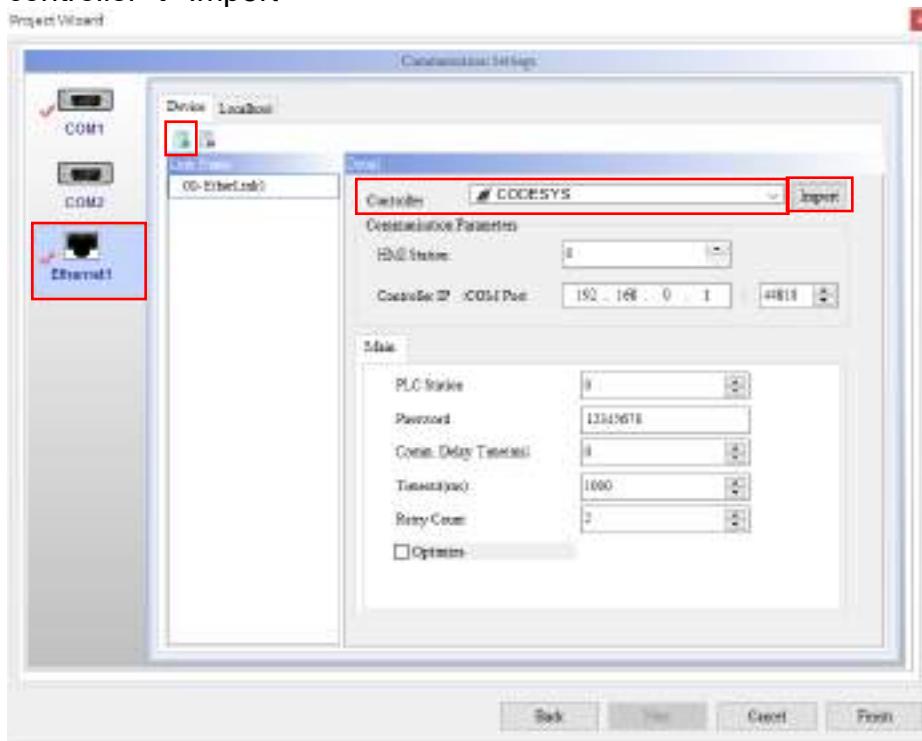


2.4 DIAScreen with PAC AX-8 Series

1. Open DIAScreenV1.0 → “New File” → Choose “DOP-100” series → Next

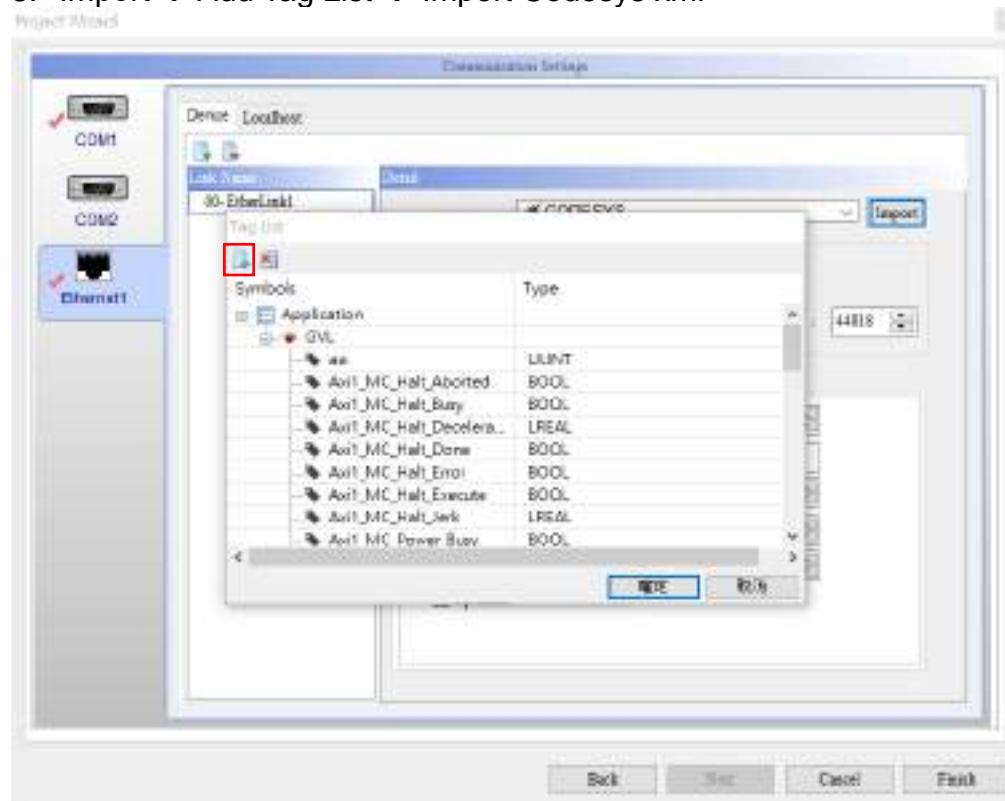


2. Project Wizard → Ethernet 1 → New Network Links → Choose “CODESYS” controller → Import



3. Import → Add Tag List → Import Codesys xml

Project Wizard



4. Insert the Element and Double click the element. User can choose the Codesys parameter to connect with the element.

